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Traffic Monitoring System Using IR Sensors

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Abstract: The project deals with counting the vehicle direction wise and also to alert the driver if there is any road block further ahead. The system is implemented using two IR sensors in each signal and main roads. When the vehicle is sensed using the first sensor the counter is incremented. When the second sensors sense the vehicle the counter is added to "vehicle count" list and the previous counter is decremented .it also stores the details of direction and location. The vehicle owner is informed about the traffic jam through a display screen placed on every main road with the details of an alternate deviation.

Keywords: IR Sensors, Microcontrollers, Bridges, Smart City Developments, LED Displays.

I. INTRODUCTION

In current world we are leading a busy life, problems like traffic jam can be really annoying. It would be helpful to know whether there is any traffic jam in a particular location before a head. For this purpose, the proposed system is been implemented. It is based on Radio Frequency deals with counting the vehicle direction wise.

This technique will consist of two IR sensors separated by specific distance fixed at a hump. When the first vehicle crosses the first hump the sensor at this hump will increment the count. When the same vehicle crosses the second hump the vehicle count at the second hump will be incremented and the count will be decremented. If there is a traffic jam and information is stored in database and directed towards the display like the system to show deviation to reach destination path. If the first sensor senses some vehicles and the second sensor doesn't sense any vehicle for a particular time then it assumes that there is a traffic jam.

The advantage of this project is that people could be informed about the traffic jam on their way and also RTO don't have to maintain the vehicle count manually by making some employees sit and 1 count the vehicle. When the vehicle pass through Toll Gate if the vehicle is permitted then Gate gets open through the sensor.

A. Traffic Management Structure

In general, traffic monitoring is mainly based on data from conventional stationary ground measurement systems such as inductive loops, radar sensors or terrestrial cameras. One handicap of these methods is the low spatial resolution depending on their distribution on the ground. New approaches include data by means of display measurement units which flow with the traffic. In order to handle traffic monitoring by remote sensing, a number of projects based on optical and SAR airborne sensors, as well as SAR satellite sensors are now running at DLR. One approach currently under development is to use infrared sensors opposite to each other in near real-time traffic management. The big advantage of the remote sensor techniques presented here is that the measurements can be applied nearly everywhere and there are no dependencies on any third party infrastructure.

By implementing this system it is possible to locate a traffic jam without manual help and at this time a message will be sent to all registered users. The message also contains the details of an alternative path. By using this system no labour is required to take the count of vehicles passing through that area thereby increasing the efficiency.

II. LITERATURE SURVEY

In Existing system, no sensor is present on the road. To count the vehicle RTO has to keep some labourers and make note of each vehicle pass by. Nowadays labourers are very expensive and no guarantee that they count each and every vehicle which pass.

It wastes people's time and it can also make businessmen lose their important deals. Not only it affects financially but also cost's a life in case of emergency. This technique will consist of two sensors separated by specific distance fixed at a hump. When the first vehicle crosses the first hump the sensor at this hump will increment the count. When the same vehicle crosses the second hump the vehicle count at the second hump will be incremented and the count will be decremented.

If there is a traffic jam it will indicate the user that the traffic is there in that area. At this time the message will be sent to all registered users.

- Currently, there is no option to know about a traffic jam occurred at a location.
- It is also impossible to count the number of vehicles traveling through a particular route. Now it is done by assigning a labor and so the result is not trustworthy.
- The existing system leads to waste of time and money.

By implementing this system it is possible to locate a traffic jam without manual help and at this time a message will be sent to all registered users. The message/screen also contains the details of an alternative path. By using this system no labour is required to take the count of vehicles passing through that area thereby increasing the efficiency. In this modulation of time, the factor of traffic jam will be detected and solved. Consumption of time is being reduced and we move through the destination within our thought limit. The display also contains the details of a deviation path

III. COMPONENTS AND REQUIREMENTS

• LCD Display Configuration

LCD display which functions where it takes the information from the controller and sensor functioning parameter and it displays the result from the binary format by generating ascii character.



Figure 1. LCD Display

• Microcontroller types

The predominant family of microcontrollers is 8-bit types since this word size has proved popular for the vast majority of tasks the devices have been required to perform. Memory expansion is possible with off chip RAM and/or ROM; for some family members, there is no on-chip ROM, or the ROMis either electrically programmable ROM (EPROM) or electrically erasable PROM (EEPROM) known as flash EEPROM which allows for the program to be erased and rewritten many times.

A microcontroller may take an input from the device it is controlling and controls the device by sending signals to different components in the device. A microcontroller is often small and low cost. The components may be chosen to minimise size and to

be as inexpensive as possible. The actual processor used to implement a microcontroller can vary widely. In many products, such as microwave ovens, the demand on the CPU is fairly low.

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Figure 2. Microcontroller

Bridges

A bridge is a device that connects two or more local area networks, or two or more segments of the same network. For example, suppose that your network includes both 10BaseT Ethernet and LocalTalk connections. You can use a bridge to connect these two networks so that they can share information with each other. In addition to connecting networks, bridges perform an additional, important function. They filter information so that network traffic intended for one portion of the network does not contest the rest of the network. (You may remember from the previous section that switches also perform the Ethernet or Local Talk (MAC) destination address. They do not attend to network routing or transport protocol information such as that carried within the TCP/IP, IPX/SPX, or Apple Talk portions of the signal.

• Software filters.

In addition to packet-screening firewalls and proxies, some school districts implement software filters that screen information based on lists of restricted sites, types of application (for example, newsgroups), or types of offensive content (such as drugs). Generally, these software applications are designed specifically for use in schools and libraries, and they include lists of sites that are recommended for restriction.

• Image Sensors

Video surveillance to monitor traffic states and detect incidents and hotspots is fairly common. It gives a comprehensive survey of the major computer vision techniques used in traffic applications. But the traditional setting for which vision algorithms exist can be seen in the lane based traffic.

Usability in developing countries, algorithms are needed for scenarios involving chaotic traffic. Preliminary work on image processing algorithms for chaotic traffic sensing is done. The algorithms are offline, so the trade-off between computation and communication is not understood. Also, the sensing accuracy itself has been tested on only a few minutes of the video clip. There are other works to use low-quality images from CCTV for traffic sensing. But computational overhead, real-timeliness, and accuracy of the designed algorithms haven't been evaluated. Thus though vision based traffic sensing for chaotic traffic seems feasible, there are several aspects that still need careful evaluation. In comparison,

Infrared Sensors

There are two types of infrared (IR) detectors; these are as follows;

Active infrared sensors operate by transmitting energy from either a light emitting diode (LED) or a laser diode. A passive infrared system detects energy emitted by objects in the field of view and may use signal-processing algorithms to extract the desired information. All objects emit some form of energy, which is in the form of heat or thermal radiation, this radiation most often falls in the infrared spectrum.

Radiation cannot be seen by the naked eye but can be detected by an infrared sensor that accepts and interprets it. In some infrared sensor like motion detectors, radiation enters the front and reaches the sensor itself at the center of the device.

Personal Computer (PC) and Memory

The PC is interfaced with the microcontroller in order to provide all time traffic control to the administrator. This is done through serial port communication. To initiate the serial communication administrator has to configure the Communication port. Whenever administrator commands the microcontroller to send recorded data, the microcontroller sends all data, in terms of vehicle count recorded according to recording intervals, to the computer. The microcontroller also sends the running configuration of parameters (Vehicle range values, delays, recording interval) on a traffic light.

• LED/Traffic Lights

A traffic signal controller system Personal Computer in which all timing related details are fed to the PC and then the control signals are passed to an 89C51 based board which light controls the various led LED traffic lights. According to the vehicle, density information corresponding LED signal lights should glow to pass the traffic.

• Segment Display

In traffic signals, seven segment displays are interfaced with the counter and controller, depending on the commands received; the counter displays the amount of waiting time. It is connected to pins of Port 1. Common Anode Connection which is suitable for this application. The microcontroller's timer is interfaced with seven segment display to display the delay of light

• Regulated Power Supply

As per the power requirement of the hardware of the intelligent traffic light control and monitoring system, the supply of +5V with respect to GND is developed. The complete circuitry is operated with TTL logic level of 0V to 5V. It comprises of 0V to 9V transformer to step down the 220V AC supply to 9V AC. Further, a bridge rectifier converts the 9V into $9V\sqrt{2}$ DC. It is further filtered through a 1000uF capacitor and then regulated using 7805 to get +5V. To isolate the output voltage of +5V from noise further filtering 220uF capacitor is used

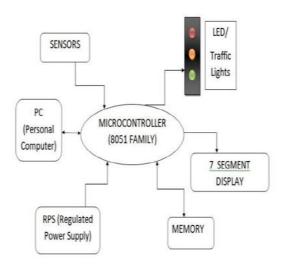


Figure 3. Block Diagram of Vehicle Detection Technique

• Vehicle Detection Technique

Traffic congestion leads to long and unpredictable commute times, environmental pollution and fuel waste. These negative effects are acuter in developing countries like India, where infrastructure growth is slow because of cost and bureaucratic issues. Frustration with the traffic lights results in an increase in accidents from cars moving when the traffic light, signals them to stop. Intelligent traffic management and better access to traffic information for commuters can help alleviate congestion issues to a certain extent.

IV. REQUIREMENT AND SPECIFICATION

A system requirements specification (SRS) – a requirements specification for a software system is a complete description of the behaviour of a system to be developed. It includes a set of use cases that describes all the interactions the users will have with the software. In addition to use cases, the SRS also contains non-functional requirements. Non-functional requirements are requirements which impose constraints on the design or implementation (such as performance engineering requirements, quality standards or design constraints).

Modules:

- User Creation
- Login
- IR Sensor Detection
- Movement Detection
- SMS Notification
- Traffic Jam with Alternate Path

A. SPECIFIC REQUIREMENT

User Interfaces

- Man and machine interaction involve how people use the system and communicate with the system.
- It is the front end of the system.
- The goal of the user interface is to make it easier to learn and easier to use.

Hardware Interfaces

- Hard disk -10GB & above
- Monitor –standard output
- RAM 1GB or higher
- 8051 PCB
- Infra-Red Sensor x2

Software Interfaces

- OS Windows XP/7/8
- Programming language C#.Net

Communication Interfaces

Connectivity-TCP/IP and IR sensors

Operating Environment

• Processor: Any processor above 2.4GHz.

• Monitor: Standard output.

• RAM: Min 1 GB of RAM or above.

• Sensor : IR sensors

• OS : Windows XP / 2003 / 2000 / 7

Front End: Visual Studio 2010Programming Language: C#.Net

Connectivity: TCP/IPBack End: My SQL 5.0

V. SYSTEM DESIGN

A. DESCRIPTION PROGRAMS

• Architectural Design

This SRS document is intended for Users, Project Managers and Developers. The documentation consists of the scope of the project i.e. the area in which it can be used, product requirements (both functional and non-functional), the product features, constraints on the operation, and limitations of the system, glossary, and improvements that can be made in the future. The reader must first go through the scope followed by an overview and then the system features to extract the most from this document. A developer can also go through the non-functional requirement for gaining a better understanding of the product.

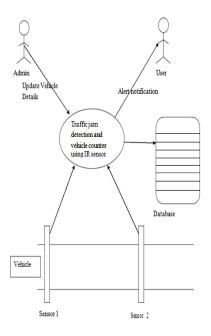


Figure 4. Architecture Diagram

An ARCHITECTURAL DESIGN is a concept that focuses on components or elements of the structure or system and unifies them into a coherent and functional whole, according to the particular approach in achieving the objectives under the given constraint and limitation.

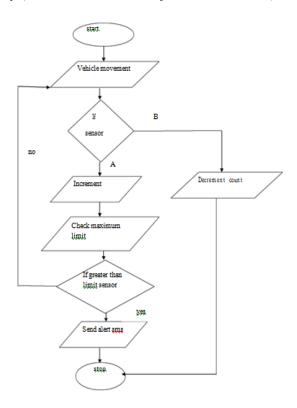
• Data Flow Diagram (DFD)

Data Flow Diagram: A Data Flow Diagram (DFD) is a graphical representation of the "flow" of data through an information system. A data flow diagram can also be used for the visualization of data processing. It is common practice for a designer to draw a context-level DFD first which shows the interaction between the system and outside entities. This context-level DFD is then "exploded" to show more detail of the system being modeled.

A DFD represents the flow of data through a system. Data flow diagrams are commonly used during problem analysis. It views a system as a function that transforms the input into desired output. A DFD shows the movement of data through the different transformations or processes in the system.

Data flow diagrams can be used to provide the end user with a physical idea of where the data they input ultimately has an effect on the structure of the whole system from order to dispatch to restock how any system is developed can be determined through a data flow diagram. The appropriate register saved in the database and maintained by appropriate authorities.

• Flow Chart For Monitoring



Use Case Diagram

There are two main actors:

- > Admin
- Vehicle

List of Use Cases:

- ✓ Admin:
 - Login
 - User Creation
 - · Add & manage Vehicle owners
 - Add Vehicle
 - Logout
- ✓ Vehicle:
 - Vehicle movement
 - Increment Count
 - Decrement Count

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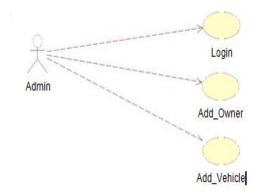


Figure 5. Use Case Diagram for Admin

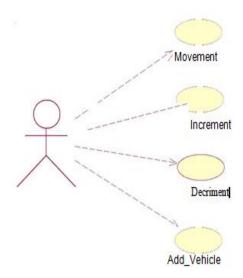


Figure 6. Use Case for Vehicle

A use case diagram at its simplest is a representation of a user's interaction with the system and depicting the specifications of a use case. A use case diagram can portray the different types of users of a system and the various ways that they interact with the system.

In software and systems engineering, a use case is a list of steps, typically defining interactions between a role and a system, to achieve a goal. The actor can be a human or an external system

• Activity Diagram

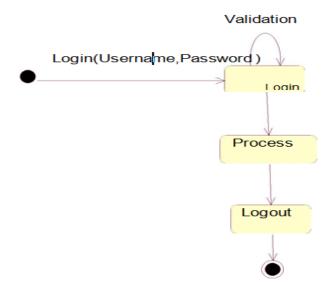


Figure 7. Activity for the Login

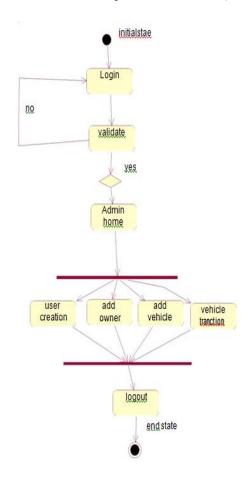
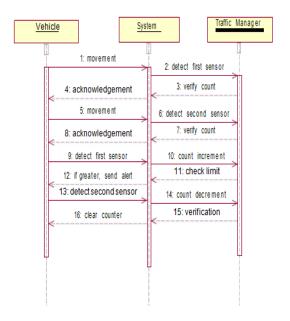


Figure 7. Activity for admin

• Sequence Diagram



 ${\bf Figure~8.~~Sequence~Diagram~for~Vehicle}$

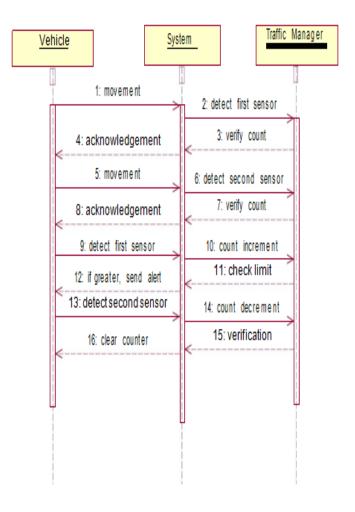


Figure 9. Sequence diagram for admin

Class Diagram

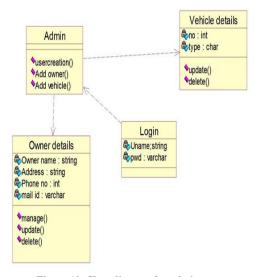


Figure 10. Class diagram for admin

VI. SOFTWARE TESTING

Software testing is the process used to help identify the correctness, completeness, security and quality of developed computer software. This includes the process of executing the program or application with the intent of finding errors. Quality is not an absolute; it is value to some person. With that in mind, testing can never completely establish the correctness of arbitrary computer software; testing furnishes a criticism or comparison that compares the state and behaviour of the product against a specification.

Testing forms the first step in determining the errors in a program. Clearly, the success of testing in revealing errors in programs depends critically on the test cases. Because the code is the only product that can be executed and whose actual behaviour can be observed, testing is the phase where the errors remaining from all the previous phases must be detected.

The program to be tested is executed with a set of test cases and the output of the program for the test cases are evaluated to determine if the programming is performing as expected. Testing forms the first step in determining errors in a program. The success of testing in revealing errors in programs depends critically on the test cases.

TABLE 1. TESTING FOR DELETION

Test case	Input	Test description	Output
1	Deletion attempted when no entries are present	Entries, if not present, cannot be deleted	Appropriate error message
2	Valid deletion	Valid deletion	Entries deleted

TABLE 2.TESTING FOR VALID USERNAME

Test case	Input	Test description	Output
1	User name is	Use name cannot be	Must enter
	Special characters	Special Characters	Characters
	or numbers	or numbers	
2	User name is left	User name cannot	Enter the User name
	blank	be left blank	

Test case	Input	Test description	Output
1	Click on logout	Logouts from	Logouts from
1	Chek on logout	particular user type	particular user type
		-	and redirects to
			login page
2	Click on clear	Entering details	Record is not
			submitted to the
			database and Text
			boxes cleared
3	Click on Submit	Entering details	Record is submitted
			to the database
4	Click on Submit	Not entering the	Appropriate error
		details	message is
			displayed
5	Click on Drop down	Selecting data	Data is displayed
	1ist		

VII. MODULE OF THE PROJECT

• FUNCTIONAL REQUIREMENT

> User Creation

Here the admin creates the different officers to handle the data of the registered users.

Input: username, password, type Output: a new user is created

Processing: if duplicate username is entered error message is displayed

> Login

This module says that only the authenticated users can access the system.

Input: username, password Output: User logs in

Processing: if duplicate login is entered error message is displayed

> IR Sensor Detection:

This module detects the vehicle and increases or decreases the count based on the vehicle density.

Input : Movement

Output : Vehicle is detected

> Movement Detection

This module detects the vehicle movements and increases the count if the second sensor doesn't detect any vehicle movement for the specific period and the interrupt is recorded in the system.

Input : Movement
Output : Sensor is detected

Traffic Jam

The traffic congestion is detected and managed using the sensors.

Input: No of vehicles

Output: Exceeds maximum limit

Alternate path

The alternate path details will be sent to the registered user

Input: Exceeds maximum limit Output: Alternate route is displayed

• NON FUNCTIONAL REQUIREMENT

- **Ease of use:** This system is user-friendly, any user with basic knowledge cane uses the system.
- **Security**: The details are secure. The admin and the user assigned by the admin can use the system and make the necessary changes. Proper information is sent to the display with appropriate deviation.
- > Maintainability: This project can be easily maintained. The details can be easily added, deleted and updated.
- > Accessibility: It is accessible to all the users especially for the visually impaired person.
- **Reliability:** This project is reliable since its coding is easy and can be easily maintained. It is easy to use the system only if the person has basic knowledge of using the system.

CONCLUSION

The project has been successfully completed. The system is implemented to detect traffic jam and to inform all the registered users about that. This will help to avoid wastage of time. Also, it can be implemented to count the number of vehicles and thereby no labour charge is required. In all, the project was concluded successfully to the satisfaction of the concerned authorities.

The main purpose of the project is

- > To detect the traffic jam
- > To Informs the registered users about traffic jam
- Provides the details of an alternative path
- ➤ It saves time and money.

FUTURE ENHANCEMENT

In future vehicles can have IR sensor fixed to number plate and using this sensor can be communicated by using signals and hence path sending an alert message using built-in GSM modem. In this, we can eliminate manually detecting hardware and also send SMS without using the internet. The vehicles having GPS settings in it can be provided with the alternative path on their screen.

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