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## Smart Agricultural Pesticide Spraying Robo

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### ABSTRACT

*This paper introduces an autonomous pesticide spraying robot designed for precision agriculture applications. With the escalating demand for sustainable farming practices, the need for efficient pest management solutions has become paramount. The proposed robot employs a combination of advanced technologies, including artificial intelligence, robotics, and sensing capabilities, to optimize pesticide application while minimizing environmental impact. Through real-time data collection and analysis, the robot identifies pest-infested areas and precisely administers the required amount of pesticide, thereby reducing chemical usage and increasing crop yield. Additionally, the robot's autonomous navigation system enables it to manoeuvre through complex terrain with minimal human intervention, enhancing operational efficiency and reducing labor costs. The integration of Internet of Things (IoT) connectivity facilitates remote monitoring and control, allowing farmers to manage spraying operations and receive actionable insights for decision-making remotely. Overall, the autonomous pesticide spraying robot represents a promising solution for sustainable agriculture, offering increased productivity, reduced environmental footprint, and improved crop health.*

**Keywords:** Robot, Smart, Crop, Internet of Things (IoT)

### 1. INTRODUCTION

The agricultural sector is facing increasing pressure to adopt sustainable practices to meet growing global food demands while minimizing environmental impact. Traditional pesticide spraying methods often involve indiscriminate application, leading to chemical runoff, soil degradation, and potential harm to non-target organisms. To address these challenges, there is a growing interest in the development of autonomous pesticide spraying robots for precision agriculture. These robots leverage cutting-edge technologies to precisely administer pesticides, optimizing their effectiveness while reducing environmental harm. This

introduction sets the stage for discussing the significance of autonomous pesticide spraying robots in modern agriculture and highlights the potential benefits they offer in terms of increased efficiency, reduced chemical usage, and improved crop health. Additionally, it outlines the objectives of this paper, which aims to explore the design, capabilities, and implications of such robots in the context of smart agriculture.

In recent years, the agricultural industry has witnessed a paradigm shift towards sustainable and technology-driven practices to address the challenges of feeding a growing global population while mitigating environmental impact. One significant area of innovation is the development of autonomous systems for precision agriculture, with a focus on pesticide application. Traditional methods of pesticide spraying often lead to overuse, environmental pollution, and decreased efficacy due to indiscriminate application. Moreover, labor-intensive manual spraying processes are becoming increasingly impractical with shrinking labor forces and rising costs.

In response to these challenges, researchers and engineers have turned to robotics and artificial intelligence to revolutionize pesticide spraying practices. Autonomous pesticide spraying robots offer a promising solution by combining precision targeting, real-time monitoring, and efficient resource utilization. These robots are equipped with advanced sensors, including cameras, LiDAR, and multispectral imaging, allowing them to detect and respond to pest infestations with unprecedented accuracy.

Furthermore, the integration of artificial intelligence algorithms enables these robots to analyze vast amounts of data, including crop health indicators, weather conditions, and pest populations, to make informed spraying decisions in real time. By precisely targeting affected areas, these robots reduce chemical usage, minimize environmental contamination, and protect beneficial organisms, thereby promoting sustainable agriculture practices.

This introduction serves to underscore the significance of autonomous pesticide-spraying robots in revolutionizing modern agriculture. By enhancing efficiency, reducing environmental impact, and improving crop yield and quality, these robots represent a transformative technology poised to address the evolving needs of the agricultural industry. This paper will delve into the design, capabilities, and implications of autonomous pesticide spraying robots, providing insights into their role in advancing smart agriculture practices.

## **2. OBJECTIVE**

A smart agriculture pesticide spraying robot's typical goals are as follows:

1. **Precision:** To precisely target treatment areas while reducing the usage of pesticides and their negative effects on the environment.
2. **Efficiency:** Farmers can reduce labor costs and save time by automating spraying chores.
3. **Safety:** By using autonomous operation, human exposure to potentially dangerous substances is reduced.
4. **Monitoring:** To supply current information on pest infestations and crop health so that decisions can be made with knowledge.
5. **Adaptability:** The ability to modify spraying parameters in response to insect activity, crop type, and environmental circumstances.
6. **Integration:** To easily link with current farm management systems in order to expedite operations and analyze data.

## **3. COMPONENTS**

1. The microcontroller, Arduino UNO R3.

A master device, the Arduino Uno is an electrical prototype board built around the Atmega AVR Microcontroller, ATmega 328P.

2. Driver for L298N Motor

The L398d motor drive, which we utilized, regulates the speed and path of motors.

### 3. 9V battery

An electric battery is a power source made up of one or more electrochemical cells that can be connected externally to power electrical appliances.

### 4. Sensor

To move the car in a single direction and follow the path that it is taking.

### 5. Module for L293D Motor Driver

DC motors can be driven in either direction by the L293D, a common motor driver or motor driver integrated circuit (IC).

### 6. Servomotor SG90

A well-liked micro servo motor for DIY and hobbyist applications is the SG90. With a maximum torque of 1.8, this compact, inexpensive servo motor can rotate 180 degrees.

### 7. Water Pump

A quieter, lighter, more energy-efficient, and more portable version of the submersible water pump is called a tiny submersible pump.

### 8. DC Bo Motor

DC motor powered by a battery. Using a DC motor, electrical energy is converted to mechanical energy.

### 5. WiFi module ESP8266

It is possible to order ESP32 modules with various antenna configurations (such as PCB antennas and antenna connectors) and flash sizes to suit the requirements of various applications.

### 6. Cable jumpers

In order to connect two places to each other without soldering, jumper wires are just wires with connector pins at either end.

### 7. Circuit relay

In order to save a switching device in the circuit from potentially being destroyed by the transient, relays require a transient suppressor.

### 8. Camera

Using mobile phones, a camera is used to see live footage from a specific distance.

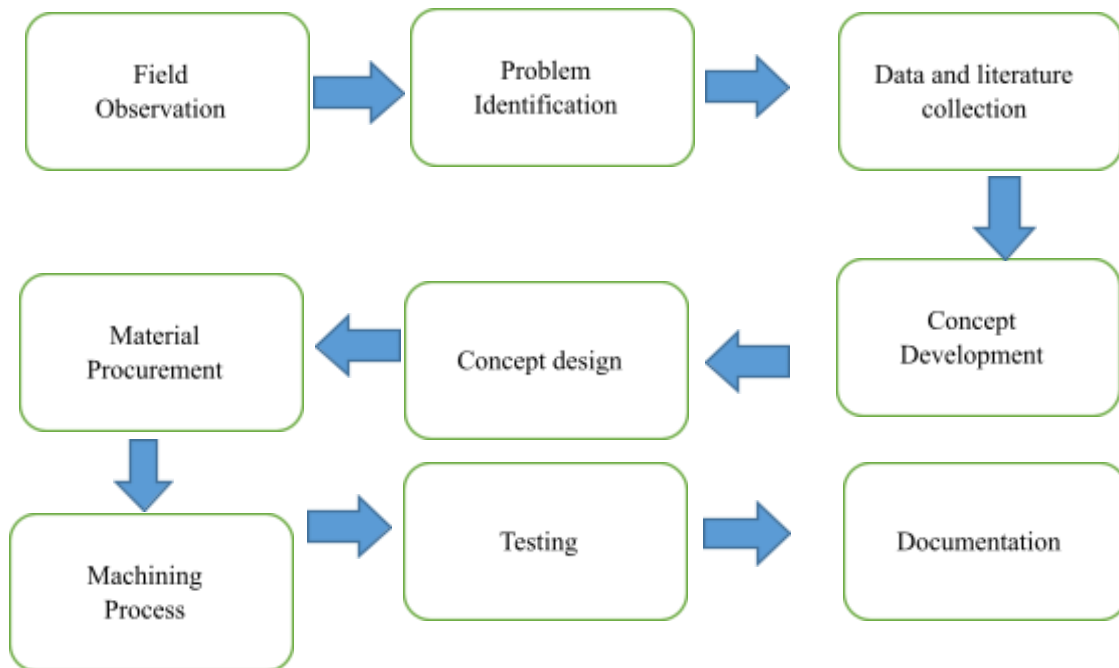
### 9. Tank

Tank The tank keeps the water at a long distance and is used to store insecticides.

## **4. METHODOLOGY**

The project's introduction and the problem specification are covered in this chapter. As a project for this topic in the academic year 2024–2025, creating a working scale model of this machine will help to overcome all the issues covered above. This methodology is broken down into several sections, each with its own title.

The sequential operations and stages that will be carried out during the project process are depicted in the flow chart below.



## 5. ADVANTAGES

The following are some benefits of using smart agricultural pesticide-spraying robots:

1. Precision Application: By precisely identifying problem areas, robots can apply fewer pesticides and have a smaller negative environmental impact.
2. Efficiency: Farmers can cover larger areas in less time thanks to automation, which reduces labor expenses and saves time when compared to manual spraying methods.
3. Reduced Exposure: Robots can lower the risk of exposure to hazardous chemicals by removing the need for human operators to handle pesticides directly.
4. Optimized Resource Management: By modifying spraying parameters in response to real-time data, robots can reduce waste and optimize pesticide dosage.
5. Enhanced Safety: Safety elements that are integrated into autonomous operation and help prevent accidents assist in guaranteeing safe operation in the field.
6. Data-driven decision-making: By collecting and analyzing field data, robots provide valuable insights into crop health, pest infestations, and environmental conditions, enabling farmers to make informed decisions.
7. Consistent Performance: Robots work consistently and precisely, providing even coverage and efficient pest management throughout the field.
8. Available 24/7: Robots may work day and night, maximizing efficiency and flexibility in scheduling jobs involving spraying, unlike human operators.

## 6. CONCLUSION

Robots that spray pesticides intelligently in agriculture provide a revolutionary answer to today's farming problems. Precision application, efficiency, decreased exposure to hazardous chemicals, optimized resource management, enhanced safety, data-

driven decision-making, consistent performance, round-the-clock availability, integration with farm management systems, and sustainability are just a few benefits that these robots offer by fusing precision technology with autonomous operation. Smart agriculture pesticide spraying robots are essential for improving productivity, profitability, and sustainability in agriculture as farming practices change to suit the needs of an expanding population and shifting environmental circumstances.

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