COMPARISON BETWEEN LINEAR SEARCH AND BINARY SEARCH ALGORITHMS

Morrice Joseph¹, Palak Keshwani²

¹BE Student, CSE Dept., KITE, Raipur(C.G)
²Assistant Professor, CSE Dept, KITE, Raipur(C.G)
E-mail: palakkeshwani@gmail.com

ABSTRACT

We are living in the age of technology. In this age of technology many engineers and researchers are comparing our existing technologies and working on new technologies. Software engineering is the most important branch of computer science. In computer science, a search algorithm is an algorithm used to solve the search problem and to retrieve information stored within some data structure. The main objective of this paper is to study linear search and binary search algorithm and to compare them on the basis of their time complexity.

Keywords: Searching, linear search, binary search, linked list, time complexity, static array, dynamic array, search algorithms.

1. Introduction

A search algorithm is the step by step procedure used to locate specific data among the collections of data. Searching is considered as the most fundamental procedure in computer science. When the data is to be searched, the difference between a fast application and a slower one lies in the use of proper search algorithms. All search algorithms make use of a search key in order to proceed with the procedure. Search algorithms are expected to return a success or a failure status, usually denoted by the Boolean true or false. Different search algorithms are available and the performance and the efficiency of them depend on the data and on the manner on which they are used.

Search cases in search algorithm can be categorized as best case, average case, and worst case. In some algorithms all three cases can be same but in some algorithms their might be big difference between all of them. The average behavior of the search algorithm helps in determining the usefulness of the algorithm.

Categories of searching

Searching algorithms are categorized into two way.

a. External searching: External searching is the searching algorithm that can handle large amount of data. The requirement of external search comes when the data being searched do not fit into the main memory of a computing device (usually RAM) and instead they must reside in the slower external memory, usually a hard drive.

b. Internal searching: The internal searching is any data searching process that takes place entirely within the main memory of the computer. This is possible whenever the data is to be searched is small enough to all be held in the main memory.
2. Description

There are two types of searching.

a. Linear search
b. Binary search

a. **Linear search**: Linear search is most simplest method of searching. It is also known as sequential search, it is named so because linear search searches element from array or linked list by testing each of the element one by one and comparing it with the search element starting from left to right. It means it is the method where search starts at the end of the list, scans the element of the list from left to right until the desired element is found. This searching is used for searching the records that are stored without considering the order.

**Algorithm for linear search:**

Linear search (Array A, Value x)
Step 1: Set i to 1
Step 2: if i>n then go to step 7
Step 3: if A[i]=x then go to step 6
Step 4: Set i to i+1
Step 5: Go to step 2
Step 6: Print element x fund at index i and go to step 8
Step 7: Print element not found
Step 8: Exit

**Pseudo code for linear search:**

Procedure linear search (list, value)
for each item in the list
if match item== value
return the item’s location
end if
end for
end procedure

b. **Binary search**: Binary search is also known as half interval search, logarithmic search, or binary chop. It is more efficient then linear search because it searches the element in minimum number of comparison. Binary search compares the target element from the middle of the element of array; if it is not found then half in which target cannot lie is eliminated and the search continues in the remaining half until the desired target is found. If the search ends with the remaining other half empty, it means the target element is not in the array.
**Algorithm for Binary search:**

Function Binary search(B, M, S):
Step 1: [Initialize]
    Low=1
    High=M
Step 2: [Perform search]
    Repeat thru step 4 while LOW<=HIGH
Step 3: [Obtain index of midpoint of interval]
    MIDDLE=(LOW+HIGH)/2
Step 4: [Compare]
    If S<B [MIDDLE]
        Then HIGH=MIDDLE-1
    Else if S>B [MIDDLE]
        Then LOW=MIDDLE+1
    Else Write('SUCCESSFULSEARCH')
        Return (MIDDLE)
Step 5: [Unsuccessful search]
    Write('UNSUCCESSFULSEARCH')
    Return(0)

**Pseudo code for Binary search**

Procedure binary search
A=sorted array
n=size of array
x=value to be searched
Set lowerBound=1
Set upperBound=n
While x not found
    If upperBound<lowerBound
        EXIT: x does not exists.
    Set midpoint= lowerBound+(upperBound-lowerBound)/2
    If A[midPoint]<x
        Set lowerBound=midpoint+1
    If A[midPoint]>x
        Set upperBound=midpoint-1
    If A[midPoint]=x
        EXIT: x found at location midpoint
End while
End procedure
3. Comparison of linear search and binary search

<table>
<thead>
<tr>
<th>S.no</th>
<th>Base of comparison</th>
<th>Linear search</th>
<th>Binary search</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Time complexity</td>
<td>$O(N)$</td>
<td>$O(\log_2 N)$</td>
</tr>
<tr>
<td>2</td>
<td>Best case time</td>
<td>$O(1)$ first element</td>
<td>$O(1)$ center element</td>
</tr>
<tr>
<td>3</td>
<td>Prerequisite of an array</td>
<td>No prerequisite</td>
<td>Array must be sorted in order</td>
</tr>
<tr>
<td>4</td>
<td>Input data</td>
<td>No need to be sorted</td>
<td>Need to be sorted</td>
</tr>
<tr>
<td>5</td>
<td>Access</td>
<td>Sequential</td>
<td>random</td>
</tr>
<tr>
<td>6</td>
<td>Comparison</td>
<td>equality</td>
<td>ordering</td>
</tr>
</tbody>
</table>

4. Conclusion

From the above research it is concluded that the linear search is more simpler than binary search because linear search searches element from array or linked list by testing each of the element one by one and compare it with the search element starting from left to right but the binary search compares the target element from the middle of the element of array; if it is not found then half in which target cannot lie is eliminated and the search continues in the remaining half until the desired target is found. But the binary search is more efficient than the linear search because it takes less amount of comparisons to find target element as compare to linear search. But the insertion of elements in binary search is not more efficient because it requires arranged elements in specific order.

5. Acknowledgement

I would like to thank my guide who gave me an opportunity to share my views regarding searching. This paper will definitely give them a detail knowledge about the searching.

6. References:


[3]. Comparing Linear Search and Binary Search Algorithms to Search an Element from a Linear List Implemented Through Static Array, Dynamic Array & Linked List(Vimal P Parmar, CK Kumbhakarna) Department of computer science, Saurashtra University, Rajkot, Gujrat,India’